

[0040] As shown in FIGS. 1 and 2, a touch panel 10 according to the embodiment has a lower substrate 11 made of a transparent substrate such as glass or a transparent plastic film and an upper substrate 12 made of a transparent and flexible substrate such as a transparent plastic film, opposing each other with a predetermined spacing therebetween. Inner surfaces of the lower substrate 11 and the upper substrate 12 respectively have a lower transparent electrode 15 and an upper transparent electrode 16, made of, e.g., indium tin oxide, formed on substantially the entire surfaces corresponding to at least an input area by a finger, a pen, or the like.

[0041] As shown in FIG. 2, the lower transparent electrode 15 is connected to wires 31 and 32 at the upper and lower sides shown in the drawing, respectively, and the upper transparent electrode 16 is connected to wires 33 and 34 at the left and right sides shown in the drawing, respectively. In the touch panel 10 according to the embodiment, the upper substrate 12 and the lower substrate 11 are assumed to lie at the operator side and the display device side having the touch panel 10, respectively.

[0042] As shown in enlarged scales in FIGS. 3 and 4, the inner surfaces of the lower substrate 11 and the upper substrate 12 can include large numbers of fine projections 21 and 22, respectively. The lower transparent electrode 15 and the upper transparent electrode 16 are formed in accordance with the configurations of the inner surfaces of the lower substrate 11 and the upper substrate 12 having the projections 21 and 22, respectively. The projections 21 and 22 are not shown in FIGS. 1 and 2, because they are too small compared to the sizes of the lower substrate 11 and the upper substrate 12, and to the spacing between these substrates.

[0043] The projections 21 and 22 may be made of members different from those of the lower substrate 11 and the upper substrate 12. As shown in FIGS. 3 and 4, however, the projections 21 and 22 are preferably integrated with the lower substrate 11 and the upper substrate 12, respectively, so as to simplify the fabrication step for the projections 21 and 22. Techniques for integrally forming the projections 21 and 22 with the lower substrate 11 and the upper substrate 12, respectively, include a method in which a mold having a pattern of the projections 21 and 22 is pushed into one of the surfaces of a flat plastic film which is softened by heating. The shapes and the patterns of the projections 21 and 22 will be described in greater detail later.

[0044] The spacing between the lower substrate 11 and the upper substrate 12, having the lower transparent electrode 15 and upper transparent electrode 16, respectively, i.e., the spacing between the lower transparent electrode 15 and the upper transparent electrode 16, is on the order of several micrometers, and an air space 13 is interposed between the lower substrate 11 and upper substrate 12, i.e., between the lower transparent electrode 15 and upper transparent electrode 16 as shown in FIG. 4. A large number of spherical spacers 14, each having a diameter equal to the spacing between the lower substrate 11 and the upper substrate 12 (about several micrometers), is disposed between the lower transparent electrode 15 and upper transparent electrode 16 so as to avoid contact of the lower transparent electrode 15 and upper transparent electrode 16 in the event of no input by a finger, a pen, or the like.

[0045] The resistive contact-type touch panel 10 has a structure in which the flexible upper substrate 12 is

deformed at a position of the upper substrate 12 pressed by a finger, a pen, or the like from its outer surface, causing the upper transparent electrode 16 to come into contact with the lower transparent electrode 15 at the pressed position. This structure allows the touch panel 10 to perform position detection.

[0046] The principal of the position detection in the touch panel 10 according to the embodiment will be described briefly with reference to FIG. 2. For position detection in the horizontal direction shown in the drawing, a predetermined voltage is applied across the wires 33 and 34 of the upper substrate 12 so as to provide the upper transparent electrode 16 with a potential gradient in the horizontal direction while providing the entire lower transparent electrode 15 with an equipotential. Thus, a horizontal position is detected based on the principal in which the detected voltage varies depending on the position where the lower transparent electrode 15 and the upper transparent electrode 16 are put in contact with each other by a finger, a pen, or the like.

[0047] In the meantime, position detection in the vertical direction shown in the drawing is accomplished in a similar fashion to that in the horizontal direction shown in the drawing. That is, a predetermined voltage is applied across the wires 31 and 32 of the lower substrate 11 so as to provide the lower transparent electrode 15 with a potential gradient in the vertical direction shown in the drawing while providing the entire upper transparent electrode 16 with an equipotential. Thus, a vertical position is detected based on the principal in which the detected voltage varies depending on the position where the lower transparent electrode 15 and the upper transparent electrode 16 are put in contact with each other by a finger, a pen, or the like.

[0048] With the above-described principal of position detection in the vertical and horizontal directions, a position (a coordinate point), where the lower transparent electrode 15 and the upper transparent electrode 16 are put in contact with each other by a finger, a pen, or the like, is detected.

[0049] The shapes and patterns of the projections 21 and 22 respectively formed on the inner surfaces of the lower substrate 11 and the upper substrate 12 will be described. As shown in FIGS. 3 and 4, each of the projections 21 and 22 can be formed as a truncated quadrangular pyramid. Reference numerals 21A and 22A respectively represent the bottoms of the projections 21 and 22, and reference numerals 21B and 22B respectively represent the tops of the projections 21 and 22. The cross-sectional area of each of the projections 21, parallel to the outer surface of the lower substrate 11, is formed to decrease continuously from the bottom 21A to the top 21B of the projection 21. The same applies to the combination of each of the projections 22 of the upper substrate 12, and the bottom 22A and the top 22B of the projection 22.

[0050] The bottom 21A of the projection 21 lies on the display device side (the lower side shown in the drawing) and the top 21B of the projection 21 lies on the operator side (the upper side shown in the drawing). The bottom 22A of the projection 22 lies on the operator side (the upper side shown in the drawing) and the top 22B of the projection 22 lies on the display device side (the lower side shown in the drawing).

[0051] As also shown in FIG. 3, arranged on the inner surfaces of the lower substrate 11 and the upper substrate 12