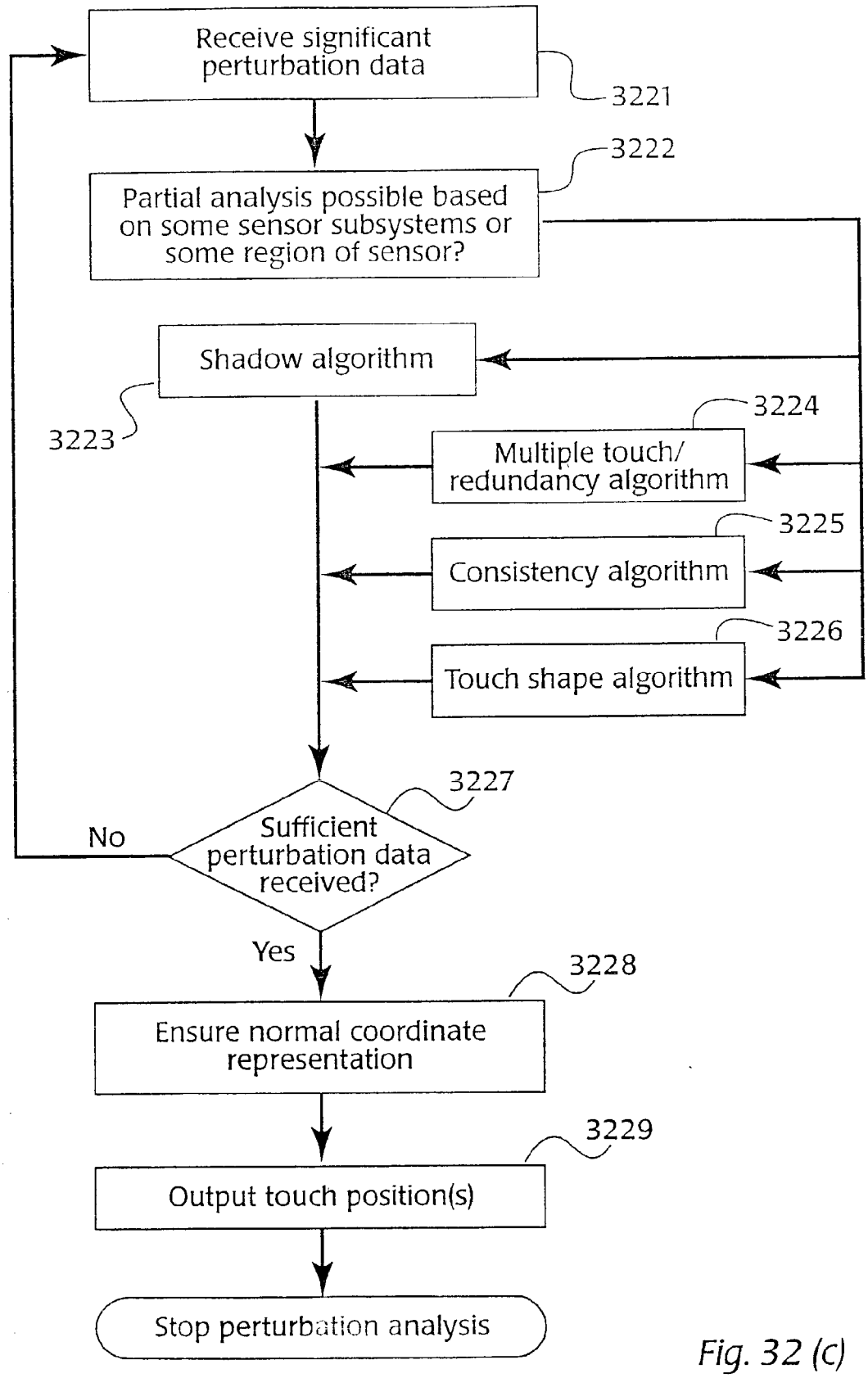
Receive significant perturbation data
3221
3222
Partial analysis possible based on some sensor subsystems or some region of sensor?
Shadow algorithm
3223
3224
Multiple touch/ redundancy algorithm
3225
Consistency algorithm
3226
Touch shape algorithm
3227
Sufficient perturbation data received?
No
Yes
3228
Ensure normal coordinate representation
3229
Output touch position(s)
Stop perturbation analysis

*Fig. 32 (c)*