

(b) binding a second lever to a second element of said limb, said second element of said limb being connected to said first element by said joint and said second lever being joined to said first lever by a hinge proximal said joint, said hinge facilitating substantially relative rotation of said first and said second levers while substantially resisting other relative motion of said levers; and

(c) altering at least one of a force and a displacement of at least one of said first lever, said second lever, and said binding of at least one for said first and said second levers in response to at least one of a treatment regimen and a sensed characteristic of at least one of said first and said second levers and said binding.

**12.** The method of claim 11 wherein the step of altering at least one of a force and a displacement of at least one of said first lever, said second lever, and said binding for at least

one of said first and said second levers in response to at least one of a treatment regimen and a sensed characteristic of at least one of said first and said second levers and said binding comprises the step of varying a length said binding in response to sensing a tension of said binding.

**13.** The method of claim 11 wherein the step of altering at least one of a force and a displacement of at least one of said first lever, said second lever, and said binding for at least one of said first and said second levers in response to at least one of a treatment regimen and a sensed characteristic of at least one of said first and said second levers and said binding comprises the step of varying a resistance to said relative rotation of said levers according to a relationship of said resistance and a sensed rotational position.

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