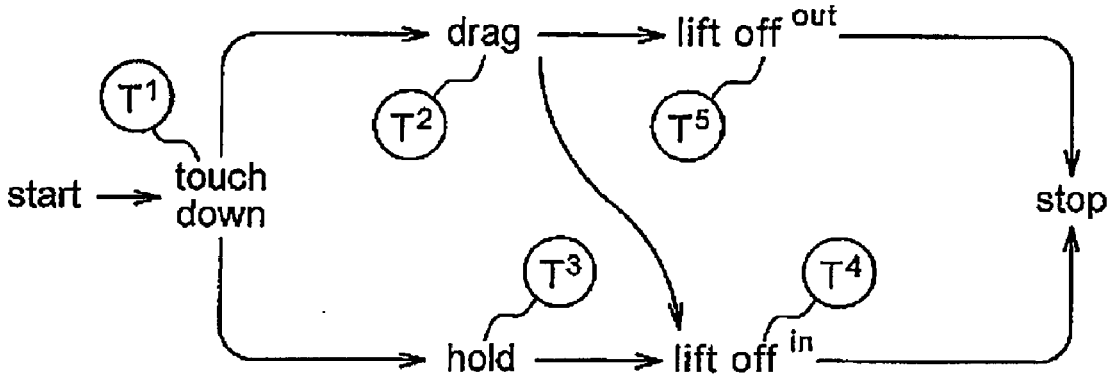
start
touch down
T1
drag
T2
lift off out
T5
hold
T3
lift off in
T4
stop

Figure 2