

[0014] In a detailed aspect of the invention, monitoring the output of each light receiving element associated with the activated light emitting element for blockage of a light beam path involves comparing the profile of the output to an expected profile having a time-based noise threshold and identifying a light beam as “noise”, “connected” or “blocked” accordingly. A beam is considered noise if there is a pulse edge in the profile prior to the noise threshold, connected if there is a pulse edge in the profile after the noise threshold and blocked in all other instances.

[0015] In a further detailed aspect, in order to identify a light beam as connected or blocked, the identification of the light beam is counted over successive triggers of the light emitting element associated with the light beam. A light beam is confirmed as being blocked or connected after the counter has reached a specified value, such as at least two successive triggers of the associated light emitting element.

[0016] These and other aspects and advantages of the invention will become apparent from the following detailed description and the accompanying drawings which illustrate by way of example the features of the invention.

#### BRIEF DESCRIPTION OF THE DRAWINGS

[0017] FIG. 1 is a planar view of a prior art touchframe system including a plurality of infrared (IR) light emitting diodes (LED) and phototransistor pairs arranged around a detection area display to form an IR grid;

[0018] FIG. 2 is an isometric view of the touchframe system of FIG. 1;

[0019] FIG. 3 is a block diagram of a touchframe system configured in accordance with the invention including a touchframe and a printed circuit board assembly (PCBA) interfacing with a graphical user interface (GUI) system;

[0020] FIG. 4 is a planar view of an exemplary configuration of the touchframe of FIG. 3 including a plurality of LEDs and infrared (IrDA) receiver positioned around the perimeter of a display;

[0021] FIG. 5 is a detailed block diagram of the PCBA of FIG. 3 including a controller and multiplexing circuitry;

[0022] FIG. 6 depicts two rows of LEDs each with an associated IrDA receiver forming overlapping triangular zones of light beam paths;

[0023] FIG. 7 depicts the directional alignment of a row of LEDs and two opposed IrDA receivers;

[0024] FIG. 8 is a schematic of the controller and multiplexing system of FIG. 3;

[0025] FIG. 9 is a timing diagram illustrating the optical noise immunity feature of the touchframe system;

[0026] FIG. 10 is a schematic representation of two triangular zones of light beam paths formed by the row of LEDs and the IrDA receivers of FIG. 7 with a touch event blocking some of the light beam paths;

[0027] FIG. 11 is a state diagram illustrating the progression of state values used by the touchframe system to determine whether a light beam is blocked or connected;

[0028] FIGS. 12a through 12d are schematic representations of twelve triangular zones formed by the LED rows and IrDA receivers of FIG. 4;

[0029] FIGS. 13a through 13d depict four sets of orthogonally overlapping zones which collectively cover the lower portion of the display of FIG. 4;

[0030] FIGS. 13e through 13h depict another four sets of orthogonally overlapping zones which collectively cover the lower portion of the display of FIG. 4;

[0031] FIGS. 13i and 13j depict examples of non-orthogonally overlapping triangular zones;

[0032] FIG. 14 is a schematic representation of a touch event occurring within two overlapping triangular zones along with two blocked light beam paths intersecting at the touch event;

[0033] FIG. 15 depicts a touch event blocking a plurality of light beam paths; and

[0034] FIG. 16 is a schematic representation two blocked light beam paths intersecting at a touch event

#### DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

[0035] Referring now to the drawings, which are provided for the purposes of illustration and not by way of limitation, and particularly to FIG. 3, there is shown a system 10 incorporating an infrared touchframe system 12 configured in accordance with the invention and including a touchframe 14 and printed circuit board assembly (PCBA) 16. The system 10 also includes a graphical user interface (GUI) system 18 which includes a GUI display 20 and a GUI central processing unit (CPU) 22. Detailed descriptions of the system architecture and system operation follow.

[0036] System Architecture

[0037] With reference to FIG. 4, the touchframe 14 is mounted to the GUI display 20 such that its perimeter is generally aligned with the perimeter of the GUI display. The purpose of the touchframe system 12 is to detect operator interaction with the GUI display 20 by means of locating the logical X and Y coordinate position of an operator's touch within the touchframe 14 perimeter. The operator's touch may be generated by a finger or mechanical instrument.

[0038] With continued reference to FIG. 4, the touchframe 14 includes a plurality of infrared LEDs 24 and a plurality of infrared (IrDA) receivers 42. The infrared LEDs 24 emit light beams to detect touches and operate in the wavelength of the IrDA receivers 42, which in one embodiment is between 850-900 nm. The infrared LEDs 24 are of the surface mount type, such as those manufactured by Stanley (part number DNP1102F), and are positioned around the perimeter of the touchframe 14 in six rows of contiguous LEDs. One row of LEDs 24 is centered across the top 26 of the touchframe, one across the bottom 28 of the touchframe, two on the left side 32 and two on the right side 34.

[0039] In an exemplary embodiment, there are thirty-eight LEDs 24 in the top 26 row of LEDs and thirty-eight LEDs in the bottom 28 row of LEDs. These LEDs 24 emit light beams across the large (vertical) X-axis 30 of the touchframe 14. There are fifty-six LEDs 24 along the left side 32 of the touchframe and fifty-six LEDs 24 along the right side 34 of the touchframe. These LEDs 24 emit light beams across the small (horizontal) Y-axis 36. The LEDs 24 on each side of