

volume to make these devices more economical and thereby facilitate their widespread use as disposable devices. Micro-electromechanical systems (MEMS) technology enables these goals to be achieved using a thin film device with integrated actuators. FIGS. 4A, 4B, and 4C illustrate an early prototype of a thin film optical system 140, in which this approach was shown to be effective. A further alternative 140' illustrated in FIG. 4D includes parallel cantilevered thin film optical waveguides for scanning and detectors. While it is likely that a production version of the thin film imaging system illustrated in these figures will be more compact and more suitable for volume production, the early prototype at least proves that the thin film optical device has an effective scanning capability and is usable in the present invention.

[0084] In the thin film optical device, an optical fiber 144 having a cladding 142 is actuated using an electrostatic actuator 156. However, in this case, instead of causing an optical fiber to scan, electrostatic actuators 156 act on a thin film optical waveguide 150 that is supported on a raised ledge 148. A distal portion 152 of the thin film optical waveguide is thus caused to scan in the two orthogonal directions indicated by the curved arrows in FIGS. 4A and 4B. The thin film optical waveguide is only approximately 0.005 mm in diameter. It should be noted that the scanning motion can be one-dimensional (i.e., along a single axis), or as shown, in two dimensions (along a raster pattern). Optionally, the thin film optical device can be mounted on a rod 143, which is then manually or mechanically rotated or vibrated to change the orientation or displace the single axis scan. Also provided is a lens 154 that is preferably mounted to a silicon substrate 146 (or other substrate material). As an alternative, external actuators (not shown) can be used instead of the electrostatic actuators, in which case, optical fiber 144 and lens 154 would be supported by silicon substrate 146, which would be caused to vibrate by the external actuators, causing the cantilevered thin film optical waveguide to resonantly scan. Optical fiber 144 is preferably affixed to silicon substrate 146 within a centering V notch 160 to ensure that it is aligned with thin film optical waveguide 150. Since the optical fiber is approximately 0.1 mm in diameter, care must be taken to provide accurate alignment between the ends of the optical fiber and the thin film optical waveguide.

[0085] FIGS. 4A and 4B shows the embodiment using butt-end coupling between optical fiber 144 and a thin film optical waveguide 150. To ensure appropriate alignment between the optical fiber and the thin film optical waveguide, V notch 160 precisely establishes a disposition of the optical fiber relative to the thin film optical waveguide. In the view of the embodiments shown in FIGS. 4A, 4B and 4C, light reflected back from an ROI passes through lens 154 and is received by RGB detectors 162r, 162g, and 162b, respectively. These detectors respond to the light of the corresponding color, producing a signal that is conveyed proximally to the external components, as discussed above. In FIG. 4D, separate image and diagnostic/therapeutic thin film optical waveguides are spaced apart and scanned in parallel; this embodiment uses a diagnostic "DIAG" detector 162d.

[0086] Tapered and Other Scanning Optical Fibers

[0087] Other techniques can also be used to produce a relatively small illumination PSF. For example, as shown in FIGS. 5A and 5B, a conventional optical fiber 164 includes a micro-fabricated end 168 with a taper 166. The micro-

fabricated end is formed either by etching (most preferable), micro-machining, or by pulling a heated optical fiber and then cutting the pulled fiber at its desired reduced diameter (least preferable). By chemically etching the cladding layer to a minimum thickness at the distal tip, the tapering produces no optical transmission losses. Since there are usually optical transmission losses associated with reducing the optical fiber source size during a pulling process, a reflective coating 167 can optionally be applied to the sides of the tapered waveguide. However, these procedures can be combined to generate a micro-fabricated optical fiber scanner with increased scanning frequency, FOV, and resolution. One advantage of using a scanning optical fiber having micro-fabricated end 168 is that the resonant frequency of the optical fiber shown in FIG. 5B is substantially greater than the resonant frequency of a blunt tip optical fiber that has not been micro-fabricated. However, the major advantage is the generation of much greater amplitude of tip deflection at this higher resonant frequency compared to untapered fibers. As mentioned above, the distal motion of micro-fabricated end 168 can produce linear patterns 169a and two-dimensional patterns 169b. Furthermore, the larger tip deflection has smaller lateral tip displacement, compared to optical fibers that have not been micro-fabricated. The etching process that is preferably used to produce the micro-fabricated tapered end is carried out using techniques well known to those of ordinary skill in the art.

[0088] As shown in FIG. 5C, the relative PSF and FOV of various forms of optical fibers varies depending upon the nature of the site at the distal end of the optical fiber from which the light travels toward an ROI 170. Displacements of specific optical fibers in the vibrational first, second, and third modes of resonance are indicated by dash lines in this Figure. An optical fiber 172 having a blunt end is driven to vibrate about in a single axis in a first resonance mode and emits light 174 focused by a lens 184, producing a PSF 176, which is the widest due to the larger size of the site at the distal end of the optical fiber. A PSF 182 that is the smallest is produced by light 180 from a tapered optical fiber 178 (either etched, micro-machined, or pulled as discussed above), which is driven in a higher resonance mode along a single axis. It should be noted that the physical scan distance through which this tapered optical fiber vibrates in resonance is relatively small, enabling it to be encased within a small diameter housing. Light 188 from an optical fiber 184 that is coupled to a ball lens 186 at its distal end and driven in the second mode (with a node in the ball lens) provides light that passes through a lens 185, producing an intermediate size PSF 190 covering the greatest FOV of the three configurations. The second and third mode embodiments exhibited in FIG. 5C are generally preferred because they require only a single actuator, they are relatively small in cross-sectional size, and they provide relatively high resolution, while enabling versatile scanning of an ROI.

[0089] Other modes of scanning can also be achieved that differ from the linear mode, or the rectilinear or zigzag mode noted above. FIG. 5D illustrates a variable radius or spiral scan mode of an optical fiber scanning system 200, which can be generated by a two axis piezoceramic tube actuator 206. In this embodiment, a plurality of light detectors 204 are arrayed around single piezoceramic tube actuator 206 in a simple arrangement, to produce signals indicative of the light received from an ROI (not shown in this Figure). Alternatively, a similar array of concentrically arranged and