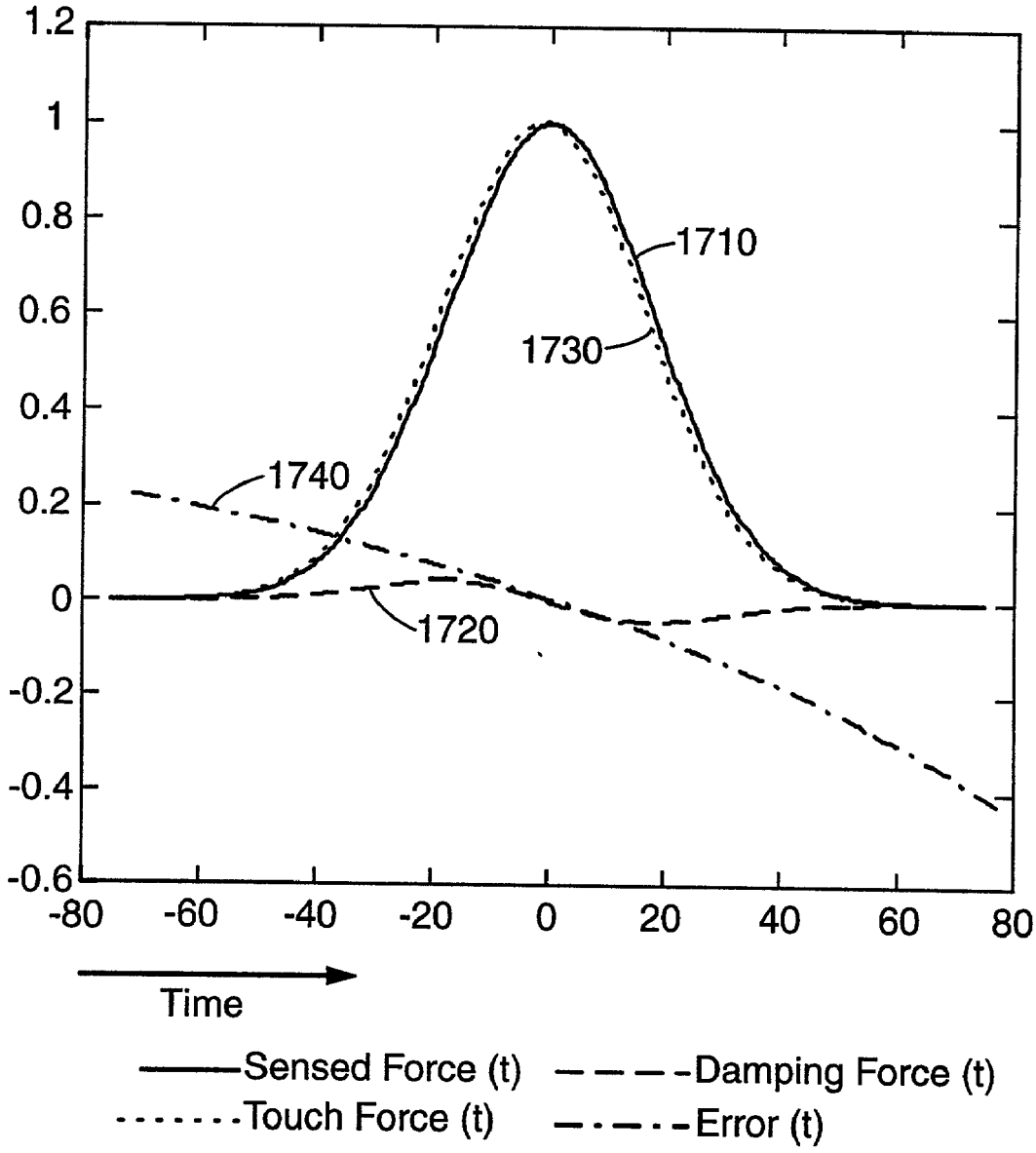
1.2
1
0.8
0.6
0.4
0.2
0
-0.2
-0.4
-0.6
-80
-60
-40
-20
0
20
40
60
80
1710
1730
1740
1720
Time
Sensed Force (t)
Damping Force (t)
Touch Force (t)
Error (t)

Fig. 17