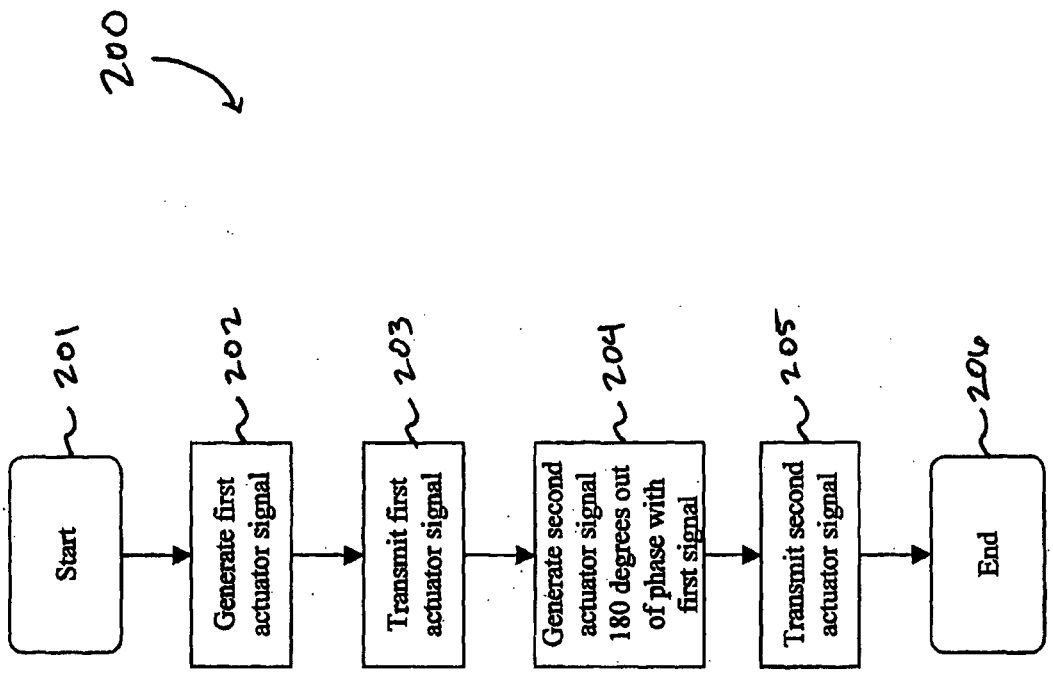
200
201
Start
202
Generate first actuator signal
203
Transmit first actuator signal
204
Generate second actuator signal 180 degrees out of phase with first signal
205
Transmit second actuator signal
206
End

Figure 2