

12. The method of claim 10 wherein the sensed contacts comprise a plurality of fingers and a portion of a hand other than a finger.

13. The method of claim 10 wherein sensed contacts comprise portions of a human hand that are within sensing range of the sensor surface but not physically touching the sensor surface.

14. The method of claim 10 wherein two or more fingers activating the sensor surface comprises a plurality of fingers initiating contact with the sensor surface.

15. The method of claim 10 wherein two or more fingers activating the sensor surface comprise a plurality of fingers terminating contact with the sensor surface.

16. A sensing apparatus comprising:

- i. a contact identification unit that examines a human hand with respect to a sensor surface and periodically produces first indications regarding the nature and position of sensed contacts, the contacts comprising identified hand parts;
- j. a simultaneous contact unit that evaluates the first indications to determine if two or more hand parts activate the sensor surface substantially simultaneously and that produces second indications identifying any such hand parts;

k. a typing unit that evaluates the first indications to determine if the character of sensed contacts is consistent with typing and produces third indications based thereon;

l. a result production unit that evaluates second indications and third indications and determines an action based thereon.

17. The apparatus of claim 16 wherein third indications comprise identification of the typing, and wherein the result production unit obviates any effects of the identification of typing if the second indication identifies such fingers.

18. The apparatus of claim 16 wherein the typing unit identifies the typing only if the second indication does not identify any such fingers.

19. The apparatus of claim 16 wherein the sensed contacts comprise a plurality of fingers and a portion of a hand other than a finger.

20. The apparatus of claim 16 wherein sensed contacts comprise portions of a human hand that are within sensing range of the sensor surface but not physically touching the sensor surface.

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