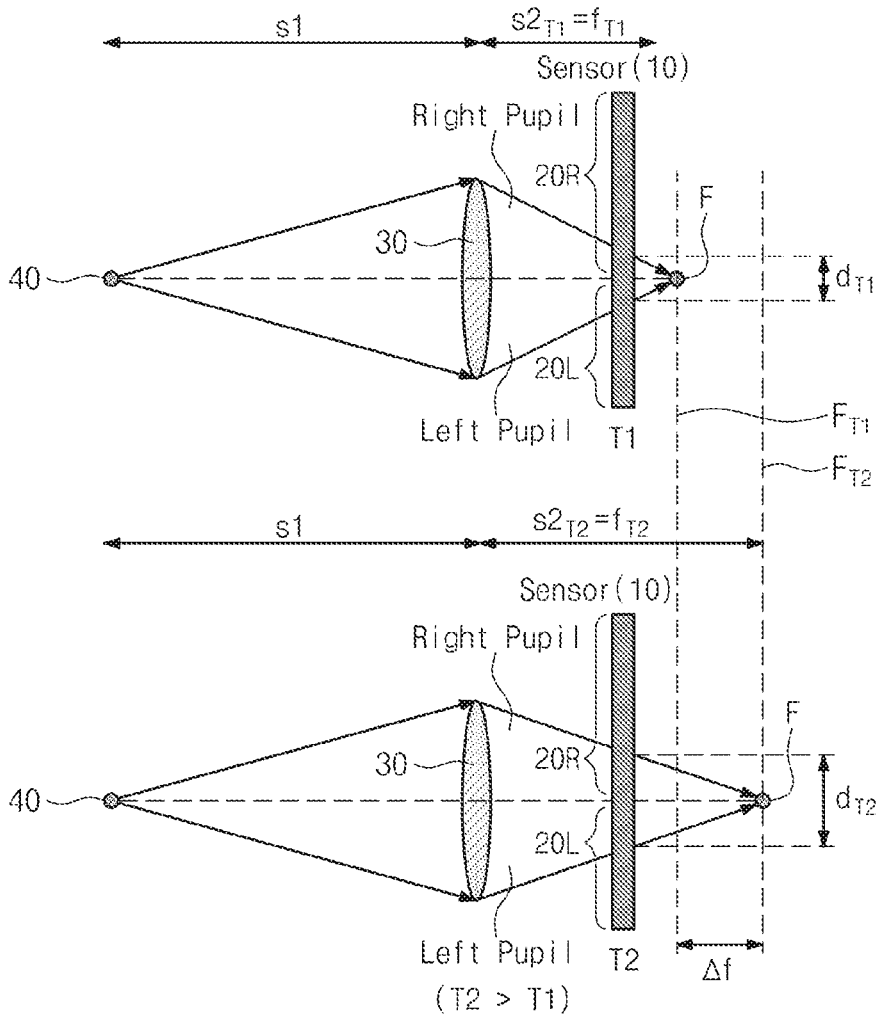
FIG. 2C


s1
s2T1=fT1
Sensor(10)
Right Pupil
20R
F
30
40
dT1
20L
Left Pupil
T1
FT1
FT2
s1
s2T2=fT2
Sensor(10)
Right Pupil
F
30
20R
40
dT2
20L
Left Pupil
T2
Δf
(T2 > T1)