

enabled in accordance with a given operative mode of said electronic device and another number of which are selectively enabled in accordance with another given operative mode of said electronic device.

7. The apparatus as defined in claim 1 wherein said input surface area is further configured for providing a variable pressure haptic operative input such that a higher pressing force corresponds to an alert to respond to a condition of said given function of said input.

8. An input module, comprising:

a substrate having at least one defined contact surface in a deformable portion of said substrate, and  
an actuator mechanism suitably arranged and configured for altering the surface topology of said substrate at said at least one defined contact surface area.

9. The input module as defined in claim 8 wherein said deformable portion of said substrate is a suitable elastomer material.

10. The input module as defined in claim 8 wherein said surface topology of said substrate at said at least one defined contact surface area protrudes beyond the surface topology of said substrate defining an input key.

11. The input module as defined in claim 8 wherein said actuator mechanism further comprises a piezoelectric motor arranged for imparting a driving force against said substrate at said at least one defined contact surface area.

12. A method, comprising:

a substrate surface topology having at least one defined contact surface area in a deformable portion of said substrate responding to a force imparted from a substrate surface topology altering mechanism, and  
a contact surface area protruding from said deformable portion of said substrate for providing a haptic operative input in response to said force imparted from said substrate surface topology altering mechanism.

13. Apparatus, comprising:

surface topology altering means for changing the topology of a substrate having at least one defined contact surface area in a deformable portion of said substrate, and  
contact surface means protruding from the surface topology of said substrate in response to said surface altering means for providing a haptic operative input.

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