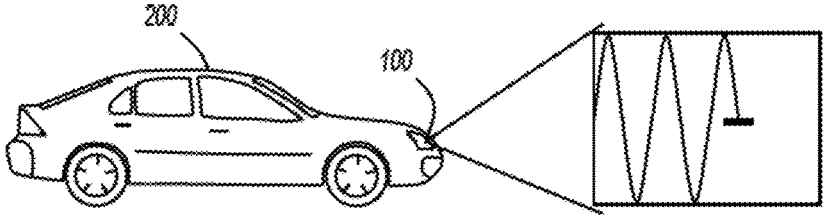
200
100

FIG. 2

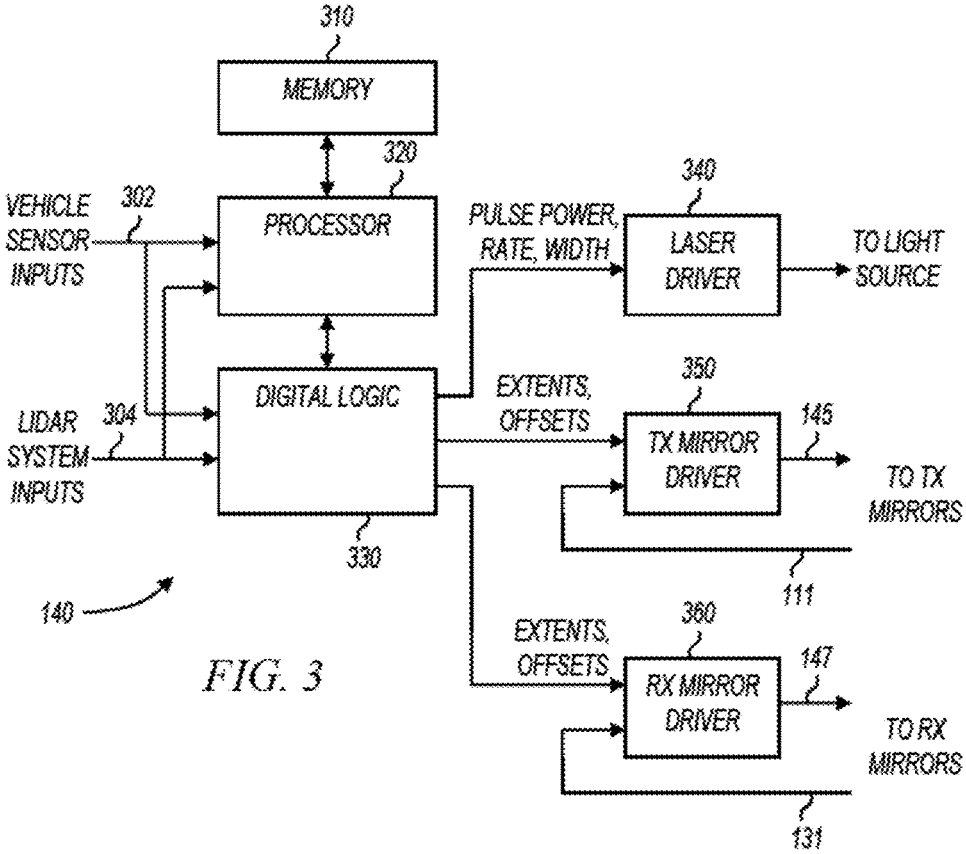
310
MEMORY
320
PROCESSOR
VEHICLE SENSOR INPUTS
302
LIDAR SYSTEM INPUTS
304
DIGITAL LOGIC
330
140
PULSE POWER, RATE, WIDTH
340
LASER DRIVER
TO LIGHT SOURCE
EXTENTS, OFFSETS
350
TX MIRROR DRIVER
145
TO TX MIRRORS
111
EXTENTS, OFFSETS
360
RX MIRROR DRIVER
147
TO RX MIRRORS
131

FIG. 3